



Robot Motion and Control 2011 (Lecture Notes in Control and Information Sciences)

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Robot Motion Control 2011 presents very recent results in robot motion and control. Forty short papers have been chosen from those presented at the sixth International Workshop on Robot Motion and Control held in Poland in June 2011. The authors of these papers have been carefully selected and represent leading institutions in this field.

The following recent developments are discussed:

Design of trajectory planning schemes for holonomic and nonholonomic systems with optimization of energy, torque limitations and other factors.

New control algorithms for industrial robots, nonholonomic systems and legged robots.

Different applications of robotic systems in industry and everyday life, like medicine, education, entertainment and others.

Multiagent systems consisting of mobile and flying robots with their applications

The book is suitable for graduate students of automation and robotics, informatics and management, mechatronics, electronics and production engineering systems as well as scientists and researchers working in these fields.

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